This listing of claims will replace all prior versions, and listings, of claims in the application:

Listing of Claims:

1. (currently amended) A method for determining the position of a medical instrument (3)-introduced into an object (1) to be examined and for imaging the vicinity of the medical instrument (3), wherein comprising the steps of

determining the position of the medical instrument (3) within the object (1) to be examined is determined by means of a localization device (5) that is arranged at the end zone of the medical instrument (3) that is to be introduced into the object during use of the medical instrument,

acquiring image information of the vicinity of the medical instrument—(3) being acquired, at the same time as said step of determining, using by means of an image acquisition device (4) arranged on the medical instrument (3),

reproducing the position of the medical instrument (3) being reproduced in a survey image (15) of the object (1) to be examined on the basis of the position determined, and displaying images of the vicinity of the object (1) to be examined which are associated each time with the relevant position being displayed on the basis of the image information acquired.

2. (currently amended) A <u>The</u> method as claimed in claim 1, characterized in that wherein the localization device comprises at least one magnetic field sensor is used as the localization device (5) whose position is determined by means of an external measuring device.

- 3. (currently amended) A The method as claimed in claim 1, characterized in that wherein the localization device comprises at least one active or passive microcoil is used as the localization device (5) whose position is determined by means of a magnetic resonance device.
- 4. (currently amended) A The method as claimed in claim 1, characterized in that wherein the localization device comprises an ultrasound sensor is used as the localization device (5).
- 5. (currently amended) A The method as claimed in claim 1, characterized in that wherein the medical instrument (3) consists at least partly of a material that can be detected by means of one of an ultrasound device or a magnetic resonance device.
- 6. A The method as claimed in claim 1, characterized in that wherein the image acquisition device is an ultrasound device, notably an intravascular ultrasound device, is used as the image acquisition device (4).
- 7. (currently amended) A The method as claimed in claim 1, eharacterized in that wherein the image acquisition device comprises an optical coherence tomography device is used as the image acquisition device (4).
- 8. (currently amended) A The method as claimed in claim 1, eharacterized in that wherein the image acquisition device comprises an MR device, notably an intravascular MR device, is used as the image acquisition device (4).

- 9. (currently amended) A The method as claimed in claim 1, characterized in that wherein the image acquisition device comprises an endoscope is used as the image acquisition device (4).
- 10. (currently amended) A device for determining the position of a medical instrument (3) introduced into an object (1) to be examined and for imaging the vicinity of the medical instrument (3), which device includes:

localization means (7) for determining the \underline{a} position of the \underline{a} medical instrument (3) within the object (1) to be examined,

a localization device (5) being arranged in the arrangeable in an end zone of the medical instrument that is to be introduced, the end zone being a part of the medical instrument that is introduced into the object during use of the medical instrument,

imaging means (6) for the acquisition at the same time of image information concerning the vicinity of the medical instrument (3),

an image acquisition device (4) being arranged arrangeable on the medical instrument (3), and

data processing and display means (12, 14) for determining and displaying the position of the medical instrument (3) localization device and displaying the position of the medical instrument in a survey image (15) of the object (1) to be examined based on the determined position of the localization device, that is, on the basis of the position thus determined, and for determining, and displaying images of the vicinity of the object (1) to be

examined, wherein said images are being associated with the relevant position, on the basis of based on the image information acquired.

- 11. (currently amended) A medical instrument (3) to be introduced into an object to be examined (4), including a localization device (5) which is arranged in the an end zone of the medical instrument that is to be introduced so as to determine the position of the medical instrument (3) within the object (1) to be examined, the end zone of the medical instrument being introduced into the object during use of the medical instrument, and an image acquisition device (4) for acquiring at the same time image information concerning the vicinity of the medical instrument (3) wherein, the position of the localization device determined being is used to determine and display the position of the medical instrument (3) in a survey image (15) of the object (1) to be examined, and the image information acquired being is used to form and display images of the vicinity associated with the relevant position of the object (1)—to be examined.
- 12. (currently amended) A The medical instrument as claimed in Claim 11, eharacterized in that wherein the medical instrument (3) is a flexible instrument, notably a catheter.
- (currently amended) A <u>computer readable medium storing a</u> computer program which includes program sections for executing the method as claimed in claim 1 <u>during</u> execution of the computer program by a <u>computer</u>.

- 14. (currently amended) A <u>computer readable medium storing a computer program</u> which includes program sections for controlling a device as claimed in claim 10 <u>during</u> execution of the computer program by a computer.
- 15. (currently amended) A <u>computer readable medium storing a computer program</u> which includes program sections for controlling a medical instrument as claimed in claim 11 during execution of the computer program by a <u>computer computer</u>.